

Ex 4.

repulsion

attraction

$$V(x_1, x_2, x) = -\frac{k_1}{2} (x_1 - x_2)^2 + \frac{k_2}{2} [(x - x_1)^2 + (x - x_2)^2]$$

$$(1.a) V_{x_1, x_2}(x) = -\frac{k_1}{2} (x_1 - x_2)^2 + k_2 \left( \frac{x_1 - x_2}{2} \right)^2 + k_2 \left( x - \frac{x_1 + x_2}{2} \right)^2$$

$$H_{el} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + \frac{2k_2}{2} \left( x - \frac{x_1 + x_2}{2} \right)^2 + V(x_1, x_2)$$

$$= -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial (\Delta x)^2} + \frac{2k_2}{2} \Delta x^2 = \hbar \omega \left( a^\dagger a + \frac{1}{2} \right), \quad \text{where } \Delta x = x_0 (a^\dagger + a)$$

$$x_0 = \sqrt{\frac{\hbar}{2m\omega}}, \quad \omega = \sqrt{\frac{2k_2}{m}}$$

$$V_{eff}(x_1, x_2) = \langle 0 | V(x_1, x_2, x) | 0 \rangle = -\frac{k_1}{2} (x_1 - x_2)^2 + k_2 \left( \frac{x_1 - x_2}{2} \right)^2 + k_2 x_0^2$$

independent of  $x_1, x_2$

$$\begin{cases} m_1 \omega^2 x_1 = \left( \frac{1}{2} k_2 - k_1 \right) x_1 - \left( \frac{1}{2} k_2 - k_1 \right) x_2 \\ m_2 \omega^2 x_2 = -\left( \frac{1}{2} k_2 - k_1 \right) x_1 + \left( \frac{1}{2} k_2 - k_1 \right) x_2 \end{cases} \rightarrow \left( \frac{1}{2} k_2 - k_1 \right) \begin{vmatrix} \frac{1}{m_1} - \lambda & -\frac{1}{m_1} \\ -\frac{1}{m_2} & \frac{1}{m_2} - \lambda \end{vmatrix} = 0, \quad \text{where } \left( \frac{1}{2} k_2 - k_1 \right) \lambda = \omega^2$$

$$\left( \frac{1}{2} k_2 - k_1 \right) \lambda \left[ \lambda - \left( \frac{1}{m_1} + \frac{1}{m_2} \right) \right] = 0 \rightarrow \begin{cases} \lambda = \omega^2 = 0 \rightarrow \text{translation} \\ \omega^2 = \left( \frac{1}{2} k_2 - k_1 \right) \left( \frac{1}{m_1} + \frac{1}{m_2} \right) \end{cases}$$

$$\text{Stable} \Rightarrow \omega^2 > 0 \Rightarrow \frac{1}{2} k_2 - k_1 > 0$$

$$(1.b) \omega = \sqrt{\left( \frac{1}{2} k_2 - k_1 \right) \left( \frac{1}{m_1} + \frac{1}{m_2} \right)}$$

(1.c) let  $\omega^2 = \lambda$

$$\begin{vmatrix} m\lambda - 2k_2 & +k_2 & +k_2 \\ k_2 & m_1 \lambda + k_1 - k_2 & -k_1 \\ k_2 & -k_1 & m_2 \lambda + k_1 - k_2 \end{vmatrix} = 0$$

In case of  $m=0$ ,

$$m_1 \lambda \{ k_2 [m_2 \lambda + (k_1 - k_2)] + k_1 k_2 \} + m_2 \lambda \{ k_2 [m_1 \lambda + (k_1 - k_2)] + k_1 k_2 \} = 0$$

$$\lambda k_2 \{ (m_1 + m_2) (2k_1 - k_2) + 2m_1 m_2 \lambda \} = 0$$

$$\omega^2 = \lambda = \left( \frac{1}{m_1} + \frac{1}{m_2} \right) \left( \frac{1}{2} k_2 - k_1 \right)$$

In the case of  $m_1 = m_2 = m$ ,

$$\begin{vmatrix} m\lambda - 2k_2 & k_2 & k_2 \\ k_2 & m_1\lambda + k_1 - k_2 & -k_1 \\ k_2 & -k_1 & m_2\lambda + k_1 - k_2 \end{vmatrix} R_1 = R_1 + R_2 + R_3 = \begin{vmatrix} m\lambda & m_1\lambda & m_2\lambda \\ k_2 & m_1\lambda + (k_1 + k_2) & -k_1 \\ k_2 & -k_1 & m_2\lambda + (k_1 + k_2) \end{vmatrix} \quad m_1 = m_2 = m$$

$$\begin{matrix} R_2 = R_2 - R_3 \\ C_2 = C_2 + C_3 \end{matrix} \begin{vmatrix} m\lambda & 2m\lambda & m\lambda \\ 0 & 0 & -m\lambda - (2k_1 + k_2) \\ k_2 & m\lambda + k_2 & m\lambda + (k_1 - k_2) \end{vmatrix} = 0$$

$$m\lambda \{ (m\lambda - k_2) [m\lambda + (2k_1 - k_2)] \} - 2m\lambda k_2 [m\lambda + (2k_1 - k_2)] = 0$$

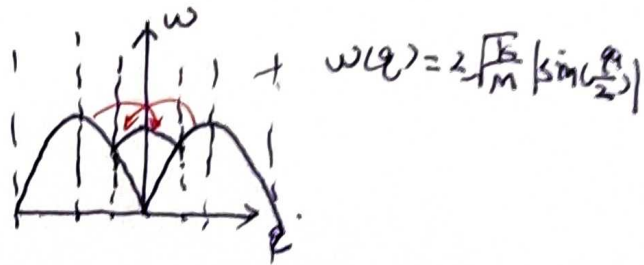
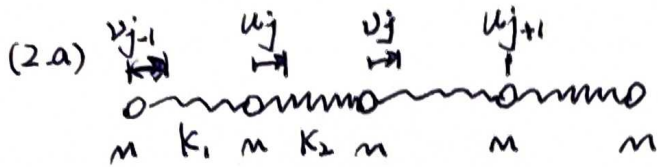
$$\lambda [m\lambda + (2k_1 - k_2)] \{ m\lambda - m k_2 - 2m k_2 \} = 0$$

$$\begin{cases} \lambda_0 = 0 \\ \lambda_1 = \frac{\frac{1}{2}k_2 - k_1}{m/2} \end{cases} \quad \begin{matrix} \text{translation} \\ \text{M} \rightleftarrows \text{M} \end{matrix}$$

nuc ↔ nuc .

$$\lambda_2 = \left( \frac{1}{2m} + \frac{1}{m} \right) 2k_2 \quad \begin{matrix} \text{Com of} \\ \text{M} \rightleftarrows \text{M} \end{matrix} \quad \text{el} \leftrightarrow \text{geometric center}$$

In reference frame of  $m_1, m_2$ , its geometric center will move with nuc-nuc vib but for  $m_1 = m_2 = m$ , geometric center coincide with Com, thus <sup>at</sup> relatively rest.



$$V = \sum_j \frac{1}{2} k_1 (v_{j-1} - u_j)^2 + \frac{1}{2} k_2 (u_j - v_j)^2$$

or  $-m\ddot{u}_j = \{ (k_1+k_2)u_j - k_1 v_{j-1} - k_2 v_j \}$       $u_q = \sum_j e^{-i\vec{q}\cdot\vec{R}_j} u_j = \sum_n e^{-iq(2na)} \cdot u_n$

$-M\ddot{v}_j = \{ (k_1+k_2)v_j - k_1 u_{j+1} - k_2 u_j \}$       $v_q = \sum_n e^{-iq(2n+1)a} v_j$

Substitute  $u_q, v_q$

$$-M\ddot{u}_q = -M \sum_n e^{-iq\cdot 2an} \ddot{u}_n = \sum_n e^{-iq\cdot 2an} \{ (k_1+k_2)u_n - k_1 u_{n-1} - k_2 u_{n+1} \}$$

$$= (k_1+k_2)u_q - k_1 e^{-iqa} v_q - k_2 e^{+iqa} v_q$$

$$-M\ddot{v}_q = (k_1+k_2)v_q - k_1 e^{+iqa} u_q - k_2 e^{-iqa} u_q$$

Solving 2x2 system of each q-sector

$$\begin{pmatrix} k_1+k_2 & -k_1 e^{+iqa} - k_2 e^{-iqa} \\ -k_1 e^{-iqa} - k_2 e^{+iqa} & k_1+k_2 \end{pmatrix} \begin{pmatrix} u_q \\ v_q \end{pmatrix} = M\omega^2 \begin{pmatrix} u_q \\ v_q \end{pmatrix}$$

$$\{ (k_1+k_2) - \lambda \}^2 - (k_1 e^{+iqa} + k_2 e^{-iqa})(k_1 e^{-iqa} + k_2 e^{+iqa}) = 0$$

$$\lambda^2 - 2(k_1+k_2)\lambda + 4k_1 k_2 \sin^2(qa) = 0$$

$$M\omega_{\pm}^2 = \lambda_{\pm} = (k_1+k_2) \pm \sqrt{(k_1+k_2)^2 - 4k_1 k_2 \sin^2(qa)}$$

$$= k_2 \{ (1+\alpha) \pm \sqrt{(1+\alpha)^2 - 4\alpha \sin^2(qa)} \}$$

In the case of  $\alpha = 1$

$$M\omega_{\pm}^2 = k_2 \{ 2 \pm 2 \cos(qa) \}$$

$$= 2k_2 \{ 1 \pm \cos(qa) \}$$

$$\omega_- = 2\sqrt{\frac{k}{M}} \left| \sin\left(\frac{qa}{2}\right) \right|$$

$$\omega_+ = 2\sqrt{\frac{k}{M}} \left| \cos\left(\frac{qa}{2}\right) \right|$$

In the case of  $\alpha \ll 1$ ,  $\sqrt{1+2x} \approx 1+x$

$$M\omega_{\pm}^2 = k_2 \{ (1+\alpha) \pm [1 + \alpha(1 - 2\sin^2(qa))] \}$$

$$\omega_- = 2\sqrt{\frac{k_1}{M}} \sin^2(qa) = 2k_1 \sin^2(qa)$$

$$\omega_- = \sqrt{\frac{2k_1}{M}} \left| \sin(qa) \right|$$

$$\alpha \ll 1, M\omega_+^2 = 2k_2, \omega_+ = \sqrt{\frac{2k_2}{M}}$$