



For  $\langle \Phi \rangle = v T_3$ , the unbroken generator is  $T_3$ , which means that transformations by  $U = e^{i\varphi T_3}$  are a symmetry, but transformations by  $U = e^{i\varphi T_{1,2}}$  are not.

→ The remaining symmetry is  $U(1)$ .

(3) •  $\Phi \rightarrow (v+h)T^3 + \varphi_1 T^1 + \varphi_2 T^2 \rightarrow \Phi^a = \begin{pmatrix} \varphi_1 \\ \varphi_2 \\ v+h \end{pmatrix}$

$$V = \frac{\lambda}{4} (\Phi^a \Phi^a - v^2)^2$$

$$= \frac{\lambda}{4} (\varphi_1^2 + \varphi_2^2 + \cancel{v^2} + 2vh + h^2 - \cancel{v^2})^2 \quad (1)$$

keep only mass terms  
 $\Downarrow$   
 $\Rightarrow 2v^2 h^2$

• We obtained two massless fields  $\varphi_1, \varphi_2$  and one massive field  $h$  with mass  $m_h = \sqrt{2\lambda} v$

• From (1) we can see the remaining  $U(1)$

symmetry:  $h \mapsto h$

$$\begin{pmatrix} \varphi_1 \\ \varphi_2 \end{pmatrix} \mapsto O \begin{pmatrix} \varphi_1 \\ \varphi_2 \end{pmatrix} \quad \text{with } O \in SO(2) \simeq U(1)$$

(4) •  $\mathcal{L} = -\frac{1}{2} \text{Tr}(G_{\mu\nu} G^{\mu\nu}) + \text{Tr}((D_\mu \Phi)^\dagger (D^\mu \Phi)) - \lambda \left( \text{Tr}(\Phi^\dagger \Phi) - \frac{v^2}{2} \right)^2$

$$\begin{aligned} D_\mu \langle \Phi \rangle &= \partial_\mu \langle \Phi \rangle - i g [W_\mu, v T^3] \\ &= -i v g \epsilon_{ab3} W_\mu^b T^a \end{aligned}$$

$$\begin{aligned}
&= -ivg \epsilon_{ab3} \bar{W}_r^b T^a \\
&= -ivg (W_\mu^2 T^1 - W_\mu^1 T^2)
\end{aligned}$$

- The mass terms for the gauge fields are coming from

$$\begin{aligned}
&\text{Tr} \left[ (D_\mu \langle \phi \rangle)^\dagger (D^\mu \langle \phi \rangle) \right] \\
&= v^2 g^2 \text{Tr} \left( W_\mu^2 W_\mu^M T^1 T^1 + W_\mu^1 W_\mu^M T^2 T^2 \right. \\
&\quad \left. + W_\mu^1 W_\mu^2 T^1 T^2 + W_\mu^2 W_\mu^1 T^2 T^1 \right) \\
&\text{Tr}(T^a T^b) = \frac{\delta^{ab}}{2} \\
&\downarrow \\
&= \frac{1}{2} v^2 g^2 (W_\mu^1 W_\mu^1 + W_\mu^2 W_\mu^2)
\end{aligned}$$

→ We obtained two massive fields  $W_\mu^1, W_\mu^2$  with mass  $m_V = v \cdot g$  and one massless field  $W_\mu^3$

## Problem 2:

(1)  $\mathcal{Y}^r = -\frac{1}{8\pi} \epsilon^{\mu\alpha\beta\gamma} \epsilon_{abc} \partial_\alpha \hat{\Phi}^a \partial_\beta \hat{\Phi}^b \partial_\gamma \hat{\Phi}^c$

$$\begin{aligned}
\partial_\mu \mathcal{Y}^r = & -\frac{1}{8\pi} \epsilon^{\mu\alpha\beta\gamma} \epsilon_{abc} \left[ (\partial_\mu \partial_\alpha \hat{\Phi}^a) \partial_\beta \hat{\Phi}^b \partial_\gamma \hat{\Phi}^c \right. \\
& + \partial_\alpha \hat{\Phi}^a (\partial_\mu \partial_\beta \hat{\Phi}^b) \partial_\gamma \hat{\Phi}^c \\
& \left. + \partial_\alpha \hat{\Phi}^a \partial_\beta \hat{\Phi}^b (\partial_\mu \partial_\gamma \hat{\Phi}^c) \right] = 0,
\end{aligned}$$

because  $\underbrace{\epsilon^{\mu\alpha\beta\gamma}}_{\text{anti-sym. in } \mu, \alpha} \underbrace{\partial_\mu \partial_\alpha}_{\text{symmetric in } \mu, \alpha} = 0$

$$(2) \quad \vec{w} = \begin{pmatrix} \cos(n\varphi) \sin\Theta \\ \sin(n\varphi) \sin\Theta \\ \cos\Theta \end{pmatrix}$$

$$\varphi = \arctan\left(\frac{y}{x}\right), \quad \Theta = \arccos\left(\frac{z}{r}\right)$$

• See the solution in the Mathematics notebook.

$$(3) \quad \begin{aligned} Q &= \int d^3x \mathcal{J}^0 \\ &= -\frac{1}{8\pi} \int d^3x \varepsilon^{0ijk} \varepsilon_{abc} (\partial_i \hat{\phi}^a) (\partial_j \hat{\phi}^b) (\partial_k \hat{\phi}^c) \end{aligned}$$

$$= +\frac{1}{8\pi} \int d^3x \varepsilon_{ijk} \varepsilon_{abc} \partial_i (\hat{\phi}^a (\partial_j \hat{\phi}^b) (\partial_k \hat{\phi}^c))$$

$$\stackrel{(2)}{=} +\frac{1}{8\pi} \int d^3x \varepsilon_{ijk} \partial_i \left( n \varepsilon_{jkm} \frac{r^m}{r^3} \right)$$

$$= +\frac{n}{4\pi} \int d^3x \partial_i \left( \frac{r^i}{r^3} \right)$$

$$= +\frac{n}{4\pi} \underbrace{\int dS^i \frac{r^i}{r^3}}_{=4\pi} = n$$

Problem 3:

$$(1) \quad \mathcal{L} = -\frac{1}{2} \text{Tr}(G_{\mu\nu} G^{\mu\nu}) + \text{Tr}((D_\mu \Phi)^\dagger (D^\mu \Phi)) - \lambda \left( \text{Tr}(\Phi^\dagger \Phi) - \frac{v^2}{2} \right)^2$$

$$= -\frac{1}{4} G_{\mu\nu}^a G_a^{\mu\nu} + \frac{1}{2} (D_\mu \Phi)^a (D^\mu \Phi)^a - \frac{\lambda}{4} (\Phi^a \Phi^a - v^2)^2$$

$$= +\frac{1}{2} \underbrace{G_{0i}^a G_{0i}^a}_{=0} - \frac{1}{4} G_{ij}^a G_{ij}^a + \frac{1}{2} \underbrace{(D_0 \Phi)^a (D_0 \Phi)^a}_{=0} - \frac{1}{2} (D_i \Phi)^a (D_i \Phi)^a - \frac{\lambda}{4} (\Phi^a \Phi^a - v^2)^2$$

$$\rightarrow \mathcal{E} = \frac{1}{4} G_{ij}^a G_{ij}^a + \frac{1}{2} (D_i \Phi)^a (D_i \Phi)^a + \frac{\lambda}{4} (\Phi^a \Phi^a - v^2)^2$$

(2)

$$\bullet (D_i \vec{\Phi}) = \partial_i \vec{\Phi} + g \vec{W}_i \times \vec{\Phi}$$

$$\xrightarrow{r \rightarrow \infty} v \partial_i \hat{w} + v g \vec{W}_i \times \hat{w} \stackrel{!}{=} 0$$

$$\bullet \text{Ansatz: } \vec{W}_i \xrightarrow{r \rightarrow \infty} \frac{1}{f} (\partial_i \hat{w}) \times \hat{w} + c_i \hat{w}$$

$$v \partial_i \hat{w} + v (\partial_i \hat{w} \times \hat{w}) \times \hat{w} + v g c_i \underbrace{\hat{w} \times \hat{w}}_{=0} = 0$$

$$v \partial_i \hat{w} - v \partial_i \hat{w} \underbrace{(\hat{w} \cdot \hat{w})}_{=1} + v \underbrace{(\hat{w} \cdot \partial_i \hat{w})}_{= \frac{1}{2} \partial_i (\hat{w} \cdot \hat{w})} \hat{w} = 0$$

$$= \frac{1}{2} \partial_i (\hat{w} \cdot \hat{w}) = \frac{1}{2} \partial_i (1) = 0$$

$$v \partial_i \hat{w} - v \partial_i \hat{w} = 0 \quad \checkmark$$

(3)

$$\bullet \text{scalar product } \langle A, B \rangle = 2 \text{Tr}(AB)$$

We break the symmetry with the vacuum expectation

$$\text{value } \langle \Phi \rangle \xrightarrow{r \rightarrow \infty} v \hat{w} = v \hat{w}^a T^a$$

$$\rightarrow \text{The unbroken } SU(2) \text{ direction is } Q = \hat{w}^a T^a$$

$$\bullet F_{\mu\nu} \xrightarrow{r \rightarrow \infty} \langle Q, G_{\mu\nu} \rangle = 2 \text{Tr}(Q G_{\mu\nu})$$

$$= 2 \hat{w}^a G_{\mu\nu}^b \text{Tr}(T^a T^b)$$

$$= \hat{w}^a G_{\mu\nu}^a = \hat{w} \cdot \vec{G}_{\mu\nu}$$

$$\bullet F_{ij} \xrightarrow{r \rightarrow \infty} \hat{w} \cdot (\partial_i \vec{W}_j - \partial_j \vec{W}_i + g \vec{W}_i \times \vec{W}_j)$$

$$B_k = -\frac{1}{2} \epsilon_{kij} F_{ij}$$

$$\xrightarrow{r \rightarrow \infty} -\frac{1}{2} \epsilon_{kij} \hat{w} \cdot \partial_i \vec{W}_j - \frac{1}{2} g \epsilon_{kij} \hat{w} \cdot (\vec{W}_i \times \vec{W}_j)$$

$$\begin{aligned}
D_k &= -\frac{1}{2} \epsilon_{kij} r_{ij} \\
&\xrightarrow{r \rightarrow \infty} -\epsilon_{kij} \hat{w} \cdot \partial_i \vec{w}_j - \frac{1}{2} g \epsilon_{kij} \hat{w} \cdot (\vec{w}_i \times \vec{w}_j) \\
&= -\epsilon_{kij} \hat{w} \cdot \left( \frac{1}{g} (\partial_i \partial_j \hat{w} \times \hat{w}) + \frac{1}{g} (\partial_j \hat{w} \times \partial_i \hat{w}) \right. \\
&\quad \left. + (\partial_i c_j) \hat{w} + c_j \partial_i \hat{w} \right) \\
&\quad - \frac{1}{2} g \epsilon_{kij} \hat{w} \cdot \left( \frac{1}{g^2} (\partial_i \hat{w} \times \hat{w}) \times (\partial_j \hat{w} \times \hat{w}) + \overbrace{c_i c_j}^{\text{sym}} \hat{w} \cdot \hat{w} \right. \\
&\quad \left. + \frac{1}{g} (\partial_i \hat{w} \times \hat{w}) \cdot \hat{w} c_j + \frac{1}{g} (\partial_j \hat{w} \times \hat{w}) \cdot \hat{w} c_i \right) \\
&= -\frac{1}{g} \epsilon_{kij} \underbrace{\hat{w} \cdot (\partial_j \hat{w} \times \partial_i \hat{w})}_{= n \epsilon_{jim} \frac{r^m}{r^3} \text{ (Problem 2)}} - \epsilon_{kij} \partial_i c_j - \epsilon_{kij} c_j \underbrace{\hat{w} \cdot \partial_i \hat{w}}_{=0} \\
&\quad - \frac{1}{2} \frac{1}{g} \epsilon_{kij} (\partial_j \hat{w} \times \hat{w}) \cdot (\hat{w} \times (\partial_i \hat{w} \times \hat{w})) \\
&= + \frac{n}{g} \epsilon_{kij} \epsilon_{mij} \frac{r^m}{r^3} - \epsilon_{kij} \partial_i c_j \\
&\quad - \frac{1}{2} \frac{1}{g} \epsilon_{kij} (\partial_j \hat{w} \times \hat{w}) \cdot (\partial_i \hat{w} - \hat{w} \underbrace{(\hat{w} \cdot \partial_i \hat{w})}_{=0}) \\
&= \frac{n}{g} \cdot 2 \delta_{km} \frac{r^m}{r^3} - \epsilon_{kij} \partial_i c_j - \frac{1}{2} \frac{n}{g} \epsilon_{kij} \epsilon_{ijm} \frac{r^m}{r^3} \\
&= \frac{n}{g} \frac{r^k}{r^3} - \epsilon_{kij} \partial_i c_j
\end{aligned}$$

(4)

$$\bullet \quad r_i \vec{w}_i \cdot \hat{w} = \frac{1}{g} r_i (\partial_i \hat{w} \times \hat{w}) \cdot \hat{w} + r_i c_i \hat{w} \cdot \hat{w} = r_i c_i \stackrel{!}{=} 0$$

• gauge transformation:

$$W_\mu^a \mapsto W_\mu^a - \epsilon_{abc} \Lambda^b W_\mu^c + \frac{1}{g} \partial_\mu \Lambda^a$$

$$\vec{w}_\mu \mapsto \vec{w}_\mu - \vec{\Lambda} \times \vec{w}_\mu + \frac{1}{g} \partial_\mu \vec{\Lambda}$$

$$\bullet r_i \vec{W}_i \cdot \hat{w} \longrightarrow r_i \vec{W}_i \cdot \hat{w} - r_i (\vec{\Lambda} \times \vec{W}_i) \cdot \hat{w} + \frac{1}{g} r_i \partial_i \vec{\Lambda} \cdot \hat{w} \stackrel{!}{=} 0$$

First of all, this gauge transformation shouldn't change the direction  $\vec{\Phi} \sim \hat{w}$ .

$$\text{Since } \Phi^a \longrightarrow \Phi^a - \epsilon_{abc} \varphi^b \varphi^c$$

$$\vec{\Phi} \longrightarrow \vec{\Phi} - \vec{\Lambda} \times \vec{\Phi}$$

we have to demand  $\vec{\Lambda} \parallel \vec{\Phi} \parallel \hat{w}$ .

$$\text{Therefore, } (\vec{\Lambda} \times \vec{W}_i) \cdot \hat{w} = (\hat{w} \times \vec{\Lambda}) \cdot \vec{W}_i = 0$$

$$\bullet \vec{W}_i \cdot \hat{w} = -\frac{1}{g} \partial_i \vec{\Lambda} \cdot \hat{w} \rightarrow c_i = -\frac{1}{g} \partial_i \vec{\Lambda} \cdot \hat{w}$$

→ There is a possible gauge transformation

to get rid of  $c_i$ , i.e. we can set  $c_i = 0$

$$(5) \bullet \vec{B} = \frac{q_m}{g} \frac{\vec{r}_i}{r^3}$$

magnetic field of point charge  $\vec{B} = \frac{q_m}{4\pi} \frac{\vec{r}_i}{r^3}$

→ the magnetic charge is  $q_m = \frac{4\pi n}{g} \stackrel{n=1}{=} \frac{4\pi}{g}$