

Problem 1:

$$U \in SU(N): \quad U = e^{i\lambda^a T^a}, \quad U^\dagger U = 1, \quad \det U = 1$$

real parameters
↓
↑
complex matrices

(a = 1, ..., k)

(1)

- Let λ^a be small:

$$\begin{aligned}
 U^\dagger U &= e^{-i\lambda^a T^{a\dagger}} e^{i\lambda^a T^a} \\
 &\approx (1 - i\lambda^a T^{a\dagger})(1 + i\lambda^a T^a) \\
 &\approx 1 + i\lambda^a T^a - i\lambda^a T^{a\dagger} \stackrel{!}{=} 1 \\
 &\rightarrow T^a = T^{a\dagger}
 \end{aligned}$$

- $\det U = \det e^{i\lambda^a T^a} = e^{i\lambda^a \text{Tr} T^a} \stackrel{!}{=} 1$
- $\rightarrow \text{Tr} T^a = 0$

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Schur decomposition:

$$A = Q^\dagger U Q$$

↑ unitary ↑ upper triangular

$$\begin{aligned}
 e^A &= e^{Q^\dagger U Q} = Q^\dagger U Q + \frac{1}{2} Q^\dagger U Q^\dagger Q U Q + \dots \\
 &= Q^\dagger e^U Q
 \end{aligned}$$

$$\begin{aligned}
 \det(e^A) &= \det(Q^\dagger e^U Q) = \det e^U \\
 &= e^{\lambda_1} \cdot e^{\lambda_2} \cdot \dots \cdot e^{\lambda_N} = e^{\lambda_1 + \lambda_2 + \dots + \lambda_N} \\
 &= e^{\text{Tr} U} = e^{\text{Tr} Q A Q^\dagger} = e^{\text{Tr} A}
 \end{aligned}$$

$$M = e^A \rightarrow A = \ln M$$

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$$\det M = e^{\text{Tr} \ln M}$$

- Number of generators:

$$T^a = T^{a\dagger} \rightarrow \left. \begin{array}{l} N \text{ diagonal matrices} \\ \frac{N^2 - N}{2} \text{ real off-diagonal} \\ \frac{N^2 - N}{2} \text{ imaginary off-diagonal} \end{array} \right\} = N^2$$

$$\text{Tr} T^a = 0 \rightarrow \text{constraint on diagonal matrices} \rightarrow -1$$

$$\Rightarrow \# \text{generators} = N^2 - 1$$

(2)

SU(2)

$$\bullet \begin{pmatrix} a & b \\ c & d \end{pmatrix}^\dagger = \begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix} \stackrel{!}{=} \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$b = c^* \rightarrow \begin{pmatrix} a & b \\ b^* & d \end{pmatrix}$$

$$\text{Tr} \begin{pmatrix} a & b \\ b^* & d \end{pmatrix} \stackrel{!}{=} 0 \rightarrow a = -d$$

$$\rightarrow \begin{pmatrix} a & b \\ b^* & -a \end{pmatrix} = \begin{pmatrix} a & b_1 - ib_2 \\ b_1 + ib_2 & -a \end{pmatrix}$$

$$= a \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + b_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + b_2 \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$$

- these matrices are already orthogonal to each other (scalar product $\langle \cdot, \cdot \rangle = 2 \text{Tr}(\cdot \cdot)$).

each other (scalar product $\langle \cdot, \cdot \rangle = 2\text{Tr}(\cdot \cdot)$).

With right normalisation we obtain:

$$T_1 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad T_2 = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad T_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

SU(3)

- $T^a = T^{at}, \quad \text{Tr } T^a = 0$

$$\rightarrow \begin{pmatrix} a & b_1 - ib_2 & c_1 - ic_2 \\ b_1 + ib_2 & d & c_1 - ie_2 \\ c_1 + ic_2 & c_1 + ie_2 & -a - d \end{pmatrix}$$

$$= a \cdot \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}}_{=A} + b_1 \cdot \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + b_2 \cdot \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$+ c_1 \cdot \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} + c_2 \cdot \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} + d \cdot \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}}_{=B}$$

$$+ e_1 \cdot \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} + e_2 \cdot \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

- $\langle A, B \rangle \neq 0$

Due to convention we choose $\tilde{T}_8 = A + B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$

Normalisation gives $T_8 = \frac{1}{2\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$

Gram-Schmidt:

$$\tilde{T}_3 = A - \langle T_8, A \rangle \cdot T_8$$

$$\begin{aligned}
\tilde{T}_3 &= A - \langle T_8, A \rangle \cdot T_8 \\
&= \begin{pmatrix} 1 & & \\ & 0 & \\ & & -1 \end{pmatrix} - \frac{1}{6} \text{Tr} \left(\begin{pmatrix} 1 & & \\ & 1 & \\ & & -2 \end{pmatrix} \begin{pmatrix} 1 & & \\ & 0 & \\ & & -1 \end{pmatrix} \right) \begin{pmatrix} 1 & & \\ & 1 & \\ & & -2 \end{pmatrix} \\
&= \begin{pmatrix} 1 & & \\ & 0 & \\ & & -1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 & & \\ & 1 & \\ & & -2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & & \\ & -\frac{1}{2} & \\ & & 0 \end{pmatrix} = T_3
\end{aligned}$$

- It is straightforward to check that now all matrices are orthogonal to each other.

With the right normalisation we have:

$$T_1 = \frac{1}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad T_2 = \frac{1}{2} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad T_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$T_4 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad T_5 = \frac{1}{2} \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}$$

$$T_6 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad T_7 = \frac{1}{2} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad T_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

(3)

- $\text{rank}(G) = \dim(\text{Cartan subalgebra of } G)$

Cartan subalgebra: maximal Abelian subalgebra

\Leftrightarrow maximal set of commuting generators

practical tip: Cartan subalgebra of $SU(N)$

$\hat{=}$ set of diagonal matrices

→ $\text{rank}(SU(N)) = N-1$ (= # Casimir operators)

$$a \in \{1, \dots, N^2-1\}$$



- Casimir operator: linear combination of symmetric homogeneous polynomials in the generators that commutes with all elements of the algebra.

$$C_m = \underbrace{x_{a_1 \dots a_m}}_{\text{sym.}} T^{a_1} \dots T^{a_m} \sim \mathbb{1}$$

convention
↓
to commute with all elements

- $SU(2)$: $x_{ab} = 2 \text{Tr}(T^a T^b) = \delta_{ab}$

$$\rightarrow C_2 = T^a T^a = \frac{3}{4} \mathbb{1}$$

- $SU(3)$: $C_2 = T^a T^a$

$\text{rank}(SU(3)) = 2$ → there is one more Casimir

→ need to construct symmetric tensor out of three generators:

$$\text{Tr}(\{T^a, T^b\} T^c) =: d^{abc}$$

$$\rightarrow C_3 = d^{abc} T^a T^b T^c$$

(4)

- fundamental representation:

smallest dimensional rep.

$$SU(N): \psi \mapsto U\psi \quad \text{for some } U \in SU(N), \psi \in \mathbb{C}^N$$

$$\rightarrow \dim = N$$

- adjoint representation:

- adjoint representation:

rep. that acts on the Lie-algebra itself

$$SU(N): \quad \Phi \mapsto U\Phi U^\dagger \quad \text{for some } U \in SU(N), \Phi \in SU(N)$$

$$\rightarrow \dim = N^2 - 1$$

(5)

- $SU(2)$:

$$[T^1, T^2] = iT^3$$

$$[T^2, T^3] = iT^1$$

$$[T^1, T^3] = -iT^2$$

→ algebra closes and the structure constants

$$\text{are } f_{abc} = \epsilon_{abc}$$

- $SU(3)$:

same procedure: calculate all possible commutators and check if they are elements of the algebra.

at the end this gives:

$$f^{123} = 1$$

$$f^{147} = f^{165} = f^{246} = f^{257} = f^{345} = f^{376} = \frac{1}{2}$$

$$f^{458} = f^{678} = \frac{\sqrt{3}}{2}$$

(others zero or related to permutations)

- relation between structure constants and adjoint rep.:

$$a_i \mapsto (11^+ a_{11} \dots 11 \dots + a) \quad a^b T^b / \dots \dots T^c$$

- relation between structure constants and adjoint rep.:

$$\begin{aligned}\Phi &\longmapsto U^\dagger \Phi U \approx (1 - i\alpha_a T^a) \Phi T^b (1 + i\alpha_c T^c) \\ &\approx \Phi + i\alpha_a \Phi^b [T^b, T^a] \\ &= \Phi + \alpha_a f_{abc} \Phi^b T^c\end{aligned}$$

$$\Phi^b \longmapsto \Phi^b + \alpha_a f_{abc} \Phi^c$$

$$\rightarrow \text{adjoint rep.: } (T_{\text{adj}}^a)_{bc} \sim f_{abc}$$

Problem 2:

$$\mathcal{L} = \bar{\Psi} (i\not{\partial} - m)\Psi$$

(1) • $\mathcal{L} \longmapsto \bar{\Psi} e^{ie\alpha} (i\not{\partial} - m) e^{-ie\alpha} \Psi = \bar{\Psi} (i\not{\partial} - m)\Psi = \mathcal{L}$

- Noether current:

$$j^\mu = \frac{\partial \mathcal{L}}{\partial \partial_\mu \Psi} \delta \Psi + \frac{\partial \mathcal{L}}{\partial \partial_\mu \Psi^\dagger} \delta \Psi^\dagger$$

$$\delta \Psi = ie\alpha \Psi$$

$$j^\mu \sim (\bar{\Psi} i\gamma^\mu) (-ie\alpha \Psi)$$

$$\rightarrow j^\mu = e \bar{\Psi} \gamma^\mu \Psi$$

- equations of motion:

$$(i\not{\partial} - m)\Psi = 0$$

or equivalently

$$i(\partial_\mu \bar{\Psi}) \gamma^\mu + m \bar{\Psi} = 0$$

$$\begin{aligned} \cdot \partial_r j^r &= e (\partial_r \bar{\Psi}) \gamma^r \Psi + e \bar{\Psi} \gamma^r (\partial_r \Psi) \\ &= e (im \bar{\Psi} \gamma^r) \Psi + e \bar{\Psi} (-im \gamma^r \Psi) = 0 \end{aligned}$$

$$\cdot Q = \int d^3x j^0 = e \int d^3x \Psi^\dagger \Psi$$

(2)

$$\begin{aligned} \cdot \mathcal{L} &\mapsto \bar{\Psi} e^{ie\alpha(x)} (i\not{\partial} - m) e^{-ie\alpha(x)} \Psi \\ \text{product rule} &= \bar{\Psi} e^{ie\alpha(x)} e^{-ie\alpha(x)} (i\not{\partial} + i(-ie\partial_r \alpha(x)) \gamma^r - m) \Psi \\ &= \bar{\Psi} (i\not{\partial} - m + e \not{\partial} \alpha(x)) \Psi \end{aligned}$$

→ not invariant

(3)

$$\begin{aligned} \cdot \delta \mathcal{L} &= j^r A_r = e \bar{\Psi} \gamma^r \Psi A_r \\ &\mapsto e \bar{\Psi} \gamma^r \Psi A_r + e \bar{\Psi} \gamma^r \Psi \partial_r \alpha \end{aligned}$$

→ $\mathcal{L} = \bar{\Psi} (i\not{\partial} - m) \Psi - j^r A_r$ is invariant

(4)

$$\begin{aligned} \cdot \bar{\Psi} i\not{\partial} \Psi - j^r A_r \\ &= \bar{\Psi} (i\not{\partial}^r (\partial_r + ie A_r)) \Psi \\ &= \bar{\Psi} i\not{D} \Psi \quad \text{where} \quad D_r = \partial_r + ie A_r \end{aligned}$$

(5)

$$\cdot \mathcal{L} = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \bar{\Psi} (i\not{D} - m) \Psi$$

• equations of motion for Ψ

$$(i\not{D} - m) \Psi = 0$$

- equations of motion for A_μ

$$\frac{\partial \mathcal{L}}{\partial(\partial_\mu A_\nu)} = -\frac{1}{2} F^{\alpha\beta} \frac{\partial}{\partial(\partial_\mu A_\nu)} F_{\alpha\beta}$$

$$= -F^{\mu\nu}$$

$$\partial_\mu \left(\frac{\partial \mathcal{L}}{\partial(\partial_\mu A_\nu)} \right) = \frac{\partial \mathcal{L}}{\partial A_\nu}$$

$$-\partial_\mu F^{\mu\nu} = -j^\nu$$

$$\partial_\mu F^{\mu\nu} = e \bar{\Psi} \gamma^\nu \Psi$$

(6)

$$\bullet Q = e \int_V d^3x \Psi^\dagger \Psi = e \int_V d^3x \bar{\Psi} \gamma^0 \Psi$$

e.o.m.

$$\stackrel{!}{=} \int_V d^3x \partial_i F^{i0}$$

$$= \int_{\partial V} dS_i E^i \quad (\text{Gauß law})$$