

VI Quantum Monte-Carlo

Until now we always aimed for representations of the many-body wave functions.

However, if we are only interested in observables, we don't necessarily need representations of $|\Psi\rangle$.

Instead, we can rewrite expectation values as:

$$\begin{aligned}\langle \hat{O} \rangle &= \text{Tr} \{ \hat{\rho} \hat{O} \} \\ &= \sum_{\sigma_1, \dots, \sigma_L} \sum_{\sigma'_1, \dots, \sigma'_L} \langle \sigma_1, \dots, \sigma_L | \hat{\rho} | \sigma'_1, \dots, \sigma'_L \rangle \langle \sigma'_1, \dots, \sigma'_L | \hat{O} | \sigma_1, \dots, \sigma_L \rangle\end{aligned}$$

Let us assume \hat{O} is diagonal in the chosen basis:

$$\langle \sigma'_1, \dots, \sigma'_L | \hat{O} | \sigma_1, \dots, \sigma_L \rangle = \delta_{\sigma'_1, \sigma_1} \dots \delta_{\sigma'_L, \sigma_L} O(\sigma_1, \dots, \sigma_L)$$

$$\Rightarrow \langle \hat{O} \rangle = \sum_{\sigma_1, \dots, \sigma_L} p(\sigma_1, \dots, \sigma_L) O(\sigma_1, \dots, \sigma_L)$$

where $p(\sigma_1, \dots, \sigma_L)$ is the prob. to find the configuration $(\sigma_1, \dots, \sigma_L)$.

Assume now, that we were able to create samples $\underline{\sigma} \in \mathcal{D}^L$ where \mathcal{D} is the set of configurations per degree of freedom σ_j , distributed according to $p(\underline{\sigma})$. Let us draw N samples $\{\underline{\sigma}^n\}_{n=1 \dots N}$

then:

$$\langle \hat{O} \rangle \approx \frac{1}{N} \sum_{n=1}^N O(\underline{\sigma}^n) \equiv \bar{O}_N$$

is an approx. to $\langle \hat{O} \rangle$ in the state $\hat{\rho}$.

Now perform $M \in \mathbb{N}$ repetitions of the estimation:

$$\langle \bar{O}_N \rangle = \frac{1}{M} \sum_{m=1}^M \bar{O}_{N,m}$$

which has the estimated error:

$$\begin{aligned} \langle \delta \bar{O}_N \rangle &= \sqrt{\text{Var}[N, \hat{O}]} \\ &= \sqrt{\frac{1}{M} \sum_{m=1}^M (\bar{O}_{N,m} - \langle \bar{O}_N \rangle)^2} \end{aligned}$$

Note that the repeated sampling is required to estimate $\langle \delta \bar{O}_N \rangle$, since a direct estimation of $(\langle \bar{O} \rangle - \langle \hat{O} \rangle)^2$ would require knowledge of $\langle \hat{O} \rangle$.

Now we have:

$$\frac{1}{M} \sum_{m=1}^M (\bar{O}_{N,m} - \langle \bar{O}_N \rangle)^2 = \frac{1}{N^2} \sum_{n,n'=1}^N \frac{1}{M} \sum_{m=1}^M (O_m(\underline{\sigma}_n) - \langle \bar{O}_N \rangle) (O_m(\underline{\sigma}_{n'}) - \langle \bar{O}_N \rangle)$$

We now demand that the samples $\underline{\sigma}_n$ are drawn independently. Then we have in the limit $M \rightarrow \infty$:

$$\begin{aligned} \text{Var}[N_1 \hat{O}] &\stackrel{M \rightarrow \infty}{=} \frac{1}{N^2} \sum_{n=1}^N \int d\underline{\sigma}_n (O(\underline{\sigma}_n) p(\underline{\sigma}_n) - \langle \bar{O}_N \rangle)^2 \\ &\quad + \frac{1}{N^2} \sum_{\substack{n, n' \\ n \neq n'}}^N \int d\underline{\sigma}_n d\underline{\sigma}_{n'} (O(\underline{\sigma}_n) p(\underline{\sigma}_n) - \langle \bar{O}_N \rangle) (O(\underline{\sigma}_{n'}) p(\underline{\sigma}_{n'}) - \langle \bar{O}_N \rangle) \\ &= \langle (\hat{O} - \langle \hat{O} \rangle)^2 \rangle / N \\ &\quad + \frac{1}{N^2} \sum_{n=1}^N \left[\underbrace{\int d\underline{\sigma}_n (O(\underline{\sigma}_n) p(\underline{\sigma}_n) - \langle \bar{O}_N \rangle)}_0 \right]^2 \\ &= \text{Var}(\hat{O}) / N \end{aligned}$$

$$\Rightarrow \langle \delta \bar{O}_N \rangle = \bar{O} \pm \sqrt{\frac{\text{Var}(\hat{O})}{N}}$$

The error scales as $\frac{1}{\sqrt{N}}$!

Remarks:

- (i) For this estimation we need independent samples: $p(\underline{\sigma}_i, \underline{\sigma}_j) = p(\underline{\sigma}_i) p(\underline{\sigma}_j)$

(ii) For independent samples, we can use central limit theory, i.e. the errors $\bar{O} - \langle \bar{O}_N \rangle$ is normal distributed for N large. Then 1 σ (68%) of all samples $\{\bar{O}_N\}$ are in the interval $\pm \langle \delta \bar{O}_N \rangle$

(iii) Evaluating $O(\underline{\Omega})$ typically only scales $\sim O(L^\alpha)$ with a small integer!

Now the question remains:

How to generate independent samples distributed according to $p(\underline{\Omega})$?

Idea: Choose $\hat{g} = \frac{e^{-\beta H}}{Z_\beta}$ with $\beta \geq 0$ the inverse temperature $\beta = \frac{1}{T}$ ($k_B \equiv 1$).

(a) Given a sample $\underline{\Omega}$, we can in most practical situations evaluate $H(\underline{\Omega})$ very cheaply.

(b) From a sample $\underline{\Omega}$, we can create another sample $\underline{\Omega}'$ by noting that the ratio $\frac{p(\underline{\Omega}')}{p(\underline{\Omega})}$

is given by $e^{-\beta H(\underline{\sigma}')} / e^{-\beta H(\underline{\sigma})}$.

(c) Imagine a system is in configuration $\underline{\sigma}$.
The prob. is $p(\underline{\sigma})$ & the prob. it transitions
into $\underline{\sigma}'$ is given by:

$$p(\underline{\sigma}') \propto \frac{p(\underline{\sigma}')}{p(\underline{\sigma})} p(\underline{\sigma}) \equiv p(\underline{\sigma} \rightarrow \underline{\sigma}') p(\underline{\sigma})$$

Since $p(\underline{\sigma} \rightarrow \underline{\sigma}')$ only requires evaluation of
 $H(\underline{\sigma}')$ & $H(\underline{\sigma})$, it should be simple to
sample trajectories:

$$\underline{\sigma}_1 \rightarrow \underline{\sigma}_2 \rightarrow \underline{\sigma}_3 \rightarrow \dots$$

Now all we need to ensure is:

- $\underline{\sigma}_{n > n_0}$ created this way are independent for
some n_0

- $\underline{\sigma}_{n > n_0}$ are drawn according to the desired
 $p(\underline{\sigma}) = e^{-\beta H(\underline{\sigma})} / Z_{\beta}$

VI.1 Markov chain & Metropolis algorithm

Let $\underline{\sigma}_n, \underline{\sigma}_m \in \mathcal{D}^L$ be configurations & W_{nm} the prob. that the transition $\underline{\sigma}_n \rightarrow \underline{\sigma}_m$ occurs.

P_{nm} describes a Markov process, if:

(i) $W_{nm} \geq 0$ for all n, m

(ii) $\sum_n W_{nm} = 1$

Important: Prob. to transition from $\underline{\sigma}_n \rightarrow \underline{\sigma}_m$ must only depend on $\underline{\sigma}_n$!

We need a certain type of Markov process:

(i) all configurations must be reachable from any other configuration: $W_{nm} > 0$, $n \in \mathcal{N}$

(ii) We want to map probability distributions to probability distributions under W_{nm} :

$$p(\underline{\sigma}_m) = \sum_n W_{nm} p(\underline{\sigma}_n)$$

$$\begin{aligned} \text{Because } 1 &= \sum_u p(\Sigma_u) = \sum_u \left(\underbrace{\sum_w W_{uw}}_1 \right) p(\Sigma_u) \\ &= \sum_u p(\Sigma_u) = 1 \end{aligned}$$

There is an important consequence of these restrictions:

Denote by $\underline{P} = (p(\Sigma_1) \ p(\Sigma_2) \ \dots \ p(\Sigma_D))$ where $D = |\mathcal{D}|^L$ the number of all possible configurations. Then W_{uw} can be treated as a matrix & :

$$\underline{W}^T \cdot \underline{P} = \underline{P}$$

from condition (ii). Thus, the stationary distribution of \underline{W}^T is just the desired probability distribution $p(\Sigma)$!

It can be reached starting from any configuration & successive evolution under

W^T generates $p(\underline{\sigma})$ (Power-method !!!).

Now we can easily formalize our initial idea:

If W_{nm} satisfies $p(\underline{\sigma}_n) W_{nm} = p(\underline{\sigma}_m) W_{mn}$, then $\underline{P}(\underline{\sigma})$ is the stationary distribution of W_{nm} .

This implies: $\frac{p(\underline{\sigma}_n)}{p(\underline{\sigma}_m)} = \frac{W_{nm}}{W_{mn}}$ (compare this to $p(\underline{\sigma}_n \rightarrow \underline{\sigma}_m)$)

Sketch for $\mathcal{D} = \{\uparrow, \downarrow\}$:



Simplest realization: Flip only one spin "i"

$$W_{nm}^{[i]} = \left(\prod_{j \neq i} \delta_{\sigma_{j,m}, \sigma_{j,n}} \right) \omega_i(\sigma_i \rightarrow \bar{\sigma}_i)$$

We can show easily that varying i from $1, \dots, L$, this is a Markov process with stationary distribution $P(\sigma_{1,n}, \dots, \sigma_{L,n})$. Then we obtain

$$\frac{w_i(\uparrow \rightarrow \downarrow)}{w_i(\downarrow \rightarrow \uparrow)} = \frac{P(\sigma_{1,n}, \dots, \sigma_{i,n} = \downarrow, \dots, \sigma_{L,n})}{P(\sigma_{1,n}, \dots, \sigma_{i,n} = \uparrow, \dots, \sigma_{L,n})}$$

VI.1 Local Monte-Carlo algorithms

Markov processes with a desired stationary distribution $p(\underline{\sigma})$ can be constructed by updating only one degree of freedom at a time. Consider spin $-\frac{1}{2}$ degrees of freedom on a d -dimensional cubic lattice with L spins along each direction: $V = L^d$ spins.

The transition probabilities should satisfy detailed balance:

$$p(\underline{\sigma}_n) W_{nm} = p(\underline{\sigma}_m) W_{mn}$$

$$\Rightarrow \sum_u \vec{p}(\underline{\sigma}_u) W_{uu} = \sum_u \vec{p}(\underline{\sigma}_u) W_{uu}$$

$$= p(\underline{\sigma}_u) \sum_u W_{uu} = p(\underline{\sigma}_u)$$

i.e. detailed balance for W_{uu} w.r.t. $p(\underline{\sigma}_u)$

implies that $p(\underline{\sigma})$ is the stationary distr.!

We decompose W_{uu} into local updates:

$$W(\underline{\sigma}_u \rightarrow \underline{\sigma}_u) = \prod_{j \in V} w_{uu}^{[j]}$$

where j labels the V sites on the hypercube.

Here, $w_{uu}^{[j]}$ means keep all spins fixed except for site j :

$$w_{uu}^{[j]} = \left(\prod_{i \neq j} \delta_{\sigma_{i,u} \sigma_{i,u}} \right) W(\sigma_{j,u} \rightarrow \sigma'_{j,u}).$$

If $w_{uu}^{[j]}$ satisfy detailed balance:

$$p(\sigma_{1,u}, \dots, \sigma_{j,u}, \dots, \sigma_{V,u}) w_{uu}^{[j]} = p(\sigma_{1,u}, \dots, \sigma'_{j,u}, \dots, \sigma_{V,u}) w_{uu}^{[j]}$$

& $\omega_{nm}^{[j]}$ is Markov-process: $\sum_{j=1}^V \omega_{nm}^{[j]} = 1$, then

for V subsequent updates $\sigma_{1n} \rightarrow \sigma_{1m}, \sigma_{2n} \rightarrow \sigma_{2m}, \dots$

we get:

site 1:

$$p(\sigma_{1m}, \dots, \sigma_{Vm}) \omega_{nm}^{[1]} = p(\sigma_{1n}, \sigma_{2m}, \dots, \sigma_{Vm}) \omega_{nm}^{[1]}$$

$$\Rightarrow p(\sigma_{1m}, \dots, \sigma_{Vm}) \frac{\omega_{nm}^{[1]}}{\omega_{nm}^{[1]}} = p(\sigma_{1n}, \sigma_{2m}, \dots, \sigma_{Vm})$$

site 2:

$$p(\sigma_{1m}, \dots, \sigma_{Vm}) \omega_{nm}^{[2]} \frac{\omega_{nm}^{[1]}}{\omega_{nm}^{[1]}} = p(\sigma_{1n}, \sigma_{2n}, \sigma_{3m}, \dots, \sigma_{Vm}) \omega_{nm}^{[2]}$$

⋮

site V :

$$p(\sigma_{1m}, \dots, \sigma_{Vm}) \frac{\prod_{j=1}^V \omega_{nm}^{[j]}}{\prod_{j=1}^V \omega_{nm}^{[j]}} = p(\sigma_{1n}, \dots, \sigma_{Vm})$$

$$\Rightarrow \sum_{\sigma_{1n} \dots \sigma_{Vm}} p(\sigma_{1m}, \dots, \sigma_{Vm}) \prod_{j=1}^V \omega_{nm}^{[j]} = p(\sigma_{1n}, \dots, \sigma_{Vm}) \sum_{\sigma_{1n} \dots \sigma_{Vm}} \prod_{j=1}^V \omega_{nm}^{[j]} \quad (11)$$

using $\sum_{j \neq i} w_{ij}^{[j]}$, i.e. $w_{ij}^{[j]}$ is Markov: $= p(\sigma_{i_1}, \dots, \sigma_{i_n})$

\Rightarrow stationary distribution is again $p(\underline{\sigma})$.

Question:

How to choose now $w_{ij}^{[j]}$?

Easy, only have to fulfill Markov-conditions & detailed balance!

Note: The state space per site is small!

For spin- $\frac{1}{2}$: $u \in \{\uparrow, \downarrow\}$

Heat-bath update

$w_{ij}^{[j]}$ is chosen such that final state u is independent on initial state v :

$$\left. \begin{aligned} w_{\uparrow\uparrow}^{[j]} &= w_{\downarrow\uparrow}^{[j]} \\ w_{\uparrow\downarrow}^{[j]} &= w_{\downarrow\downarrow}^{[j]} \end{aligned} \right\} w_{ij}^{[j]} = \frac{e^{-\beta H(\sigma_{i_1}, \dots, \sigma_{j_{i-1}}, \sigma_{i+1}, \dots, \sigma_{i_n})}}{\sum_{\substack{\uparrow \\ \downarrow \\ jv = \uparrow, \downarrow}} e^{-\beta H(\sigma_{i_1}, \dots, \sigma_{j_{i-1}}, \sigma_{i+1}, \dots, \sigma_{i_n})}}$$

(12)

Clearly we have detailed balance:

$$\frac{p(\sigma_{i_1}, \dots, \sigma_{j_1}, \dots, \sigma_{V_n})}{p(\sigma_{i_n}, \dots, \sigma_{j_n}, \dots, \sigma_{V_n})} = \frac{e^{-\beta H(\sigma_{i_1}, \dots, \sigma_{j_1}, \dots, \sigma_{V_n})}}{e^{-\beta H(\sigma_{i_n}, \dots, \sigma_{j_n}, \dots, \sigma_{V_n})}} = \frac{\omega_{i_n}^{[j]}}{\omega_{i_1}^{[j]}}$$

& Markov-process: $\sum_{\sigma_{j_n}} \omega_{i_n}^{[j]} = 1$.

Metropolis update

Heat bath has a problem: It chooses new config. independent on previous config. What if σ_{i_n} is a very unlikely config? Heat bath does not care when determining $\omega_{i_n}^{[j]}$. This can be cured taking prob. of σ_{i_n} into account:

$$\omega_{\sigma_{i_n} \sigma_{j_n}}^{[j]} = \min \left(1, \frac{p(\sigma_{i_n}, \dots, \sigma_{j_n}, \dots, \sigma_{V_n})}{p(\sigma_{i_1}, \dots, \sigma_{j_1}, \dots, \sigma_{V_n})} \right)$$

If $p(\sigma_{i_n}, \dots, \sigma_{j_n}, \dots, \sigma_{V_n}) < p(\sigma_{i_1}, \dots, \sigma_{j_1}, \dots, \sigma_{V_n})$

then the new config is chosen for sure!

For spin $-\frac{1}{2}$:

$$\omega_{\sigma_n, \bar{\sigma}_n}^{[ij]} = \min\left(1, \frac{e^{-\beta H(\sigma_1, \dots, \bar{\sigma}_i, \dots, \sigma_n)}}{e^{-\beta H(\sigma_1, \dots, \sigma_i, \dots, \sigma_n)}\right)$$

$$\text{with } \bar{\sigma} = \begin{cases} \downarrow & \text{if } \sigma = \uparrow \\ \uparrow & \text{if } \sigma = \downarrow \end{cases}$$

Prove detailed balance & Markov-properties as
exercise \checkmark .

VI.2 Auto correlation time

We saw that we need statistically independent
samples $\underline{\sigma}_n$ to properly estimate the std.-dev.

For local updates $(\sigma_1, \dots, \sigma_i, \dots, \sigma_n) \rightarrow (\sigma_1, \dots, \sigma_{j+1}, \dots, \sigma_n)$

this is surely not the case.

So how many Markov-steps do we have to
take until $\underline{\sigma}_n$ & $\underline{\sigma}_{n+1}$ are independent?

Consider again the variance of an observable \hat{O} for N samples $\{\sigma_n\}$ in M independent realizations:

$$\text{Var}[N, \hat{O}] = \left\langle \left(\frac{1}{N} \sum_{n=1}^N (O[\sigma_n] - \langle \bar{O}_N \rangle) \right)^2 \right\rangle$$

where $\langle \cdot \rangle$ refers to the average over the M realizations. We now define the autocorrelation

$$\Gamma_{\hat{O}}(n-m) = \left\langle (O[\sigma_n] - \langle \bar{O}_N \rangle) (O[\sigma_m] - \langle \bar{O}_N \rangle) \right\rangle$$

$$\Rightarrow \text{Var}[N, \hat{O}] = \frac{1}{N^2} \sum_{n,m=1}^N \Gamma_{\hat{O}}(n-m)$$

$$\stackrel{M \rightarrow \infty}{=} \frac{1}{N} \text{Var}(\hat{O}) + \frac{1}{N^2} \sum_{n \neq m=1}^N \Gamma_{\hat{O}}(n-m)$$

The second vanishes for independent samples σ_n, σ_m (see VI.1) but in practice it's finite.

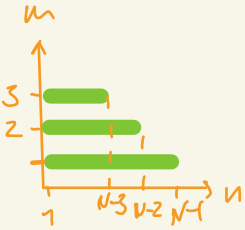
For large $|n-m|$ we get for Markov-chains:

$$\Gamma_{\hat{O}}(n-m) \sim e^{-\frac{|n-m|}{\tau}}, \quad \tau \in \mathbb{R}^+$$

(it can be shown that $\tau = -\frac{1}{n\lambda_1}$ where $\lambda_1 < 1$ is the second largest eigenvalue of W_{nn} .)

Using $\Gamma_{\hat{\theta}}(n-m) = \Gamma_{\hat{\theta}}(m-n)$ we get:

$$\begin{aligned} \sum_{\substack{n=1 \\ n \neq m=1}}^N \Gamma_{\hat{\theta}}(n-m) &= 2 \sum_{n < m}^N \Gamma_{\hat{\theta}}(n-m) \\ &= 2 \sum_{n=1}^{N-1} \sum_{m=n+1}^N \Gamma_{\hat{\theta}}(n-m) \\ &= 2 \sum_{n=1}^N \sum_{m=1}^{N-n} \Gamma_{\hat{\theta}}(m) \\ &= 2 \sum_{n=1}^{N-1} (N-n) \Gamma_{\hat{\theta}}(n) \end{aligned}$$



$$\begin{aligned} \Rightarrow \text{Var}[\hat{\theta}, N] &= \frac{\text{Var}(\hat{\theta})}{N} \left(1 + 2 \sum_{n=1}^{N-1} \left(1 - \frac{n}{N} \right) \frac{\Gamma_{\hat{\theta}}(n)}{\text{Var}(\hat{\theta})} \right) \\ &= \frac{\text{Var}(\hat{\theta})}{N} (1 + \tau_{nn}) \end{aligned}$$

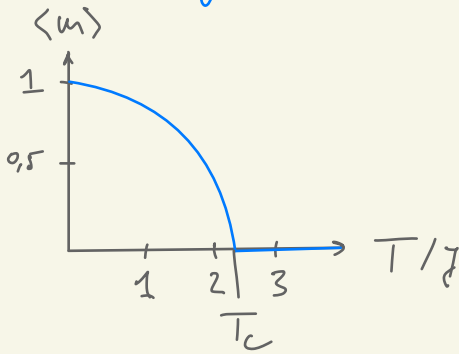
Thus, the estimator for uncorrelated samples $\frac{\text{Var}(\hat{\theta})}{N}$ is corrected by τ_{nn} !

VI.3 Cluster Monte-Carlo algorithms

Systems at temperatures $T \approx T_c$ where T_c is the critical temp. of a continuous phase transition, exhibit universal behavior. In particular the correlation lengths diverge: $\xi \sim |T - T_c|^{-\nu}$.

Example:

2D-Ising model: $\hat{H} = -J \sum_{\langle i,j \rangle} S_i^z S_j^z$



$$\langle m \rangle = \frac{1}{L^2} \sum_{j=1}^{L^2} \langle S_j^z \rangle$$

$$T_c/J = \frac{2}{2(1+\sqrt{2})} \approx 2,265$$

Correlation function:

$$\langle (S_i^z)^2 \rangle = \langle S_i^z S_j^z \rangle - \langle S_i^z \rangle \langle S_j^z \rangle \sim \begin{cases} c e^{-|i-j|/\xi} & , |T - T_c| \gg 0 \\ |T - T_c|^{-\nu} & , |T - T_c| \approx 0 \end{cases}$$

What does this mean for local updates?

Critical slow-down

For Metropolis's update the acceptance prob is

$$P_{\sigma\bar{\sigma}}^{[ij]} = \min\left(1, \frac{e^{\beta J \sum_i' \sigma_{ni} \bar{\sigma}_{nj}}}{e^{\beta J \sum_i' \sigma_{ni} \sigma_{nj}}}\right)$$

Only if "j" is at boundary of clusters we get large accept. -prob. Since \hat{H} is invariant under

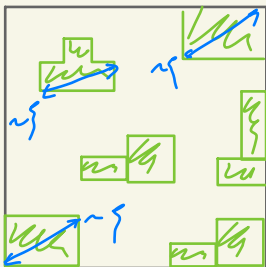
$\sigma_j \rightarrow \bar{\sigma}_j$ for all j, $P(\underline{\sigma}) = P(\bar{\underline{\sigma}})$ & we can estimate number of surface sites by covering $L^2/2$ area with patches of size ξ^2 :

$$n_{\text{patches}} = \frac{L^2}{2\xi^2} \Rightarrow \sim \frac{L}{\xi} \text{ boundary sites}$$

\Rightarrow acceptance rate becomes

$$\sim P_{\sigma\bar{\sigma}}^{[ij]} \frac{n_{\text{patches}}}{L^2} = P_{\sigma\bar{\sigma}}^{[ij]} \frac{1}{L\xi}$$

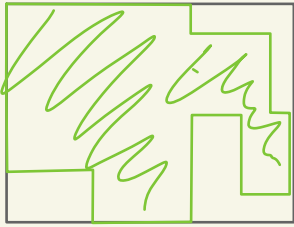
(i) $|T - T_c| \gg 0$:



Green clusters have spins aligned \uparrow . Avg. size is

$$\sim \xi \ll L \Rightarrow \frac{1}{L\xi} \sim \mathcal{O}(1)$$

(ii) $|T - T_c| \approx 0$:



Green clusters have spins aligned \uparrow . Avg. size is $\sim \xi \sim L \Rightarrow \frac{1}{L^2} \sim \frac{1}{L^2}$

Close to critical temperature, the acceptance rate goes down $\sim \frac{1}{L^2} \Rightarrow \tau_m$ diverges :

$$\tau_m \sim |T - T_c|^{-z\nu} \sim \xi^z$$

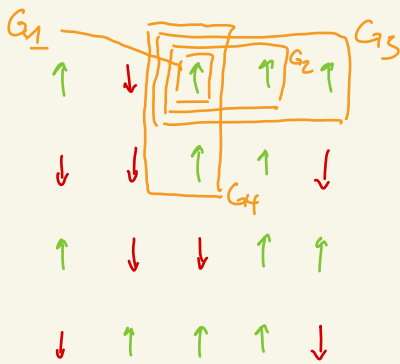
and here $z \approx 2$ (from above estimation: $\sim L^2$ samples to successfully flip one spin).

Known as critical slow-down! But this not a problem of the method; Dependency on τ_m in observable estimation comes from ω_m being local! Idea: use global updates!

Cluster decomposition

We want to derive a Markov-process satisfying detailed balance such that more than 1 site can be updated without evaluating probabilities for too many different configurations!

Consider a configuration of spin- $\frac{1}{2}$ degrees of freedom:



Note:

We can label clusters of aligned spins to this configuration:

$$\mathcal{G}_{\sigma} = \{G_1, G_2, G_3, G_4, \dots\}$$

A configuration $\underline{\sigma}$ can be decomposed into various clusters! Let's identify clusters with graphs (here bond percolation graphs) & decompose $p(\underline{\sigma})$:

$$p(\underline{\sigma}) = \sum_{G \in \mathcal{G}_{\sigma}} W(\underline{\sigma}, G) \quad \text{for all possible graphs } G \in \mathcal{G}_{\sigma}.$$

The prob. to find a certain graph G in a 120

given config $\underline{\sigma}$ is

$$P_{\underline{\sigma}}(G) = \frac{W(\underline{\sigma}, G)}{p(\underline{\sigma})}.$$

For the bond-percolation graphs we can factor W :

$$W(\underline{\sigma}, G) = V(G) \Delta(\underline{\sigma}, G)$$

where $V(G)$ is the prob. to find graph G out of all possible lattice-compatible graphs G & $\Delta(\underline{\sigma}, G)$ sorts out graphs incompatible with $\underline{\sigma}$:

$$\Delta(\underline{\sigma}, G) = \begin{cases} 1 & \text{if } G \in \mathcal{G}_{\underline{\sigma}} \\ 0 & \text{otherwise} \end{cases}$$

Now introduce a Markov process:

$$W_{nn'}^{GG'} = W_{Gn}^{[\underline{\sigma}_n]} W_{\underline{\sigma}_n \underline{\sigma}_{n'}}^{[G']}$$

where: (i) $W_{GG'}^{[\underline{\sigma}_n]}$ is transition amplitude from graph $G \rightarrow G'$ given $\underline{\sigma}_n$

(ii) $w_{\underline{\sigma}_n \underline{\sigma}_n}^{[G]}$ is transition amplitude from config $\underline{\sigma}_n \rightarrow \underline{\sigma}_n$ given G'

Detailed balance:

$$(i) P_{\underline{\sigma}_n}(h) w_{hh'}^{[\underline{\sigma}_n]} \stackrel{!}{=} P_{\underline{\sigma}_n}(h') w_{h'h}^{[\underline{\sigma}_n]}$$

if we always choose a new graph h' then

$$w_{hh'}^{[\underline{\sigma}_n]} = 1 \Rightarrow \frac{P_{\underline{\sigma}_n}(h)}{P_{\underline{\sigma}_n}(h')} = \frac{V(h)}{V(h')} = 1 \quad \checkmark$$

$$(ii) P_G(\underline{\sigma}_n) w_{nm}^{[G]} \stackrel{!}{=} P_G(\underline{\sigma}_m) w_{mn}^{[G]}$$

Here $P_G(\underline{\sigma}_n)$ is the prob. to have config $\underline{\sigma}_n$

& we can assign graph G from $\underline{\sigma}_n$:

$$P_G(\underline{\sigma}_n) = W(\underline{\sigma}_n, G)$$

$$\Rightarrow W(\underline{\sigma}_n, G) w_{nm}^{[G]} = W(\underline{\sigma}_m, G) w_{mn}^{[G]}$$

$$\Leftrightarrow \frac{V(h) \Delta(\underline{\sigma}_n, h)}{V(h) \Delta(\underline{\sigma}_m, G)} = \frac{w_{mn}^{[G]}}{w_{nm}^{[G]}}$$



1 because $\underline{\sigma}_n$ & $\underline{\sigma}_m$ compatible with

G , otherwise $w_{nm}^{[G]} = 0$ for all (n, m) !

We now only need to choose $w_{nm}^{[G]}$ to

obey $P(\underline{\sigma}) = \sum_{G \in \mathcal{G}_{\underline{\sigma}}} V(G)$.

Consider graphs constructed from aligned, neighboring spins:

Graph spins			$P(\underline{\sigma})$
$\uparrow \uparrow$	$\Delta = 1$	$\Delta = 1$	$\sim e^{+\beta J}$
$\uparrow \downarrow$	$\Delta = 0$	$\Delta = 1$	$\sim e^{-\beta J}$
$\downarrow \uparrow$	$\Delta = 0$	$\Delta = 1$	$\sim e^{-\beta J}$
$\downarrow \downarrow$	$\Delta = 1$	$\Delta = 1$	$\sim e^{+\beta J}$

For $P_{\underline{\sigma}}(G) = \begin{cases} (e^{+\beta J} + e^{-\beta J}) / e^{\beta J} & \text{if } \uparrow\uparrow \text{ or } \downarrow\downarrow \\ 0 & \text{otherwise} \end{cases}$

For $w_{nm}^{[G]}$ flip cluster of connected spins (which keeps graph G intact) with $w_{nm}^{[G]} = w_{mn}^{[G]}$.

Examples discussed on sheet 4.

Remarks

- (i) In the step $(\mathbb{S}_n, G) \rightarrow (\mathbb{S}_n, G')$ clusters are allowed to grow. Near $T = T_c$ this will happen almost surely since $P_{\mathbb{S}}(G) \neq 0$ only for aligned spins
- (ii) Away from $T = T_c$ large clusters are unlikely (only with prob. $\sim \frac{1}{L^2}$). Then updates can become very expensive
- (iii) Observing τ_n & switching from local to cluster updates is good strategy!