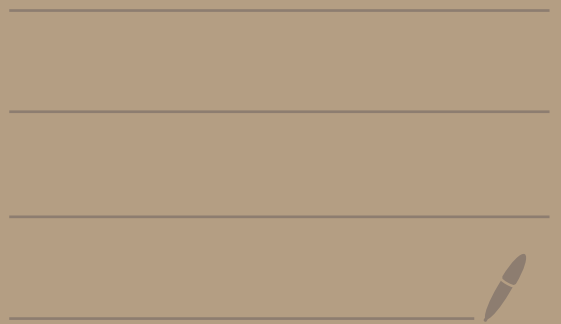


Neutrino Physics Course

Lecture XIX

15/6/2021



$$P \text{ in LR: } \$ \$ B$$

$$G_{LR} = SU(2)_L \times SU(2)_R \times U(1)_{B-L}$$

$$\Delta_L \quad \searrow \quad M_R \quad \Delta_R$$

$$SU(2)_L \times U(1)_Y$$

$$\Phi \text{ (l: -doublet)} \left. \begin{array}{l} \searrow \\ \searrow \end{array} \right\} \begin{array}{l} M_L = M_W \\ U(1)_{em} \end{array}$$

• M_R : break $SU(2)_R \times U(1)_{B-L}$

$$Y_{1/2} = T_{3R} + \frac{B-L}{2} \quad \downarrow \quad U(1)_Y$$

$$\left. \begin{array}{l} \langle \Delta_R \rangle : M_{WR} \propto \langle \Delta_R \rangle \\ M_{ZR} \propto \langle \Delta_R \rangle \end{array} \right\}$$

$\Delta_R \therefore \langle \Delta_R \rangle$ leaves only SM particles massless

$(\begin{smallmatrix} \nu \\ e \end{smallmatrix})_L$ e_R ~~ν_R~~

$(\begin{smallmatrix} u \\ d \end{smallmatrix})_L$ u_R, d_R

$\Leftrightarrow \nu_R$ must be heavy

\Downarrow

fixes Δ_R completely

\Downarrow

(SM: $m_f \neq 0 \Rightarrow$ Higgs is ϕ)



if v_R is heavy ($m_{v_R} \propto \langle \Delta_R \rangle$)

$\Rightarrow v_R$ couples to Δ_R

\Rightarrow l_R couples to Δ_R
(but not l_L)

• l_R - and only l_R - couples to Δ_R

~~$l_R \Delta_R$~~

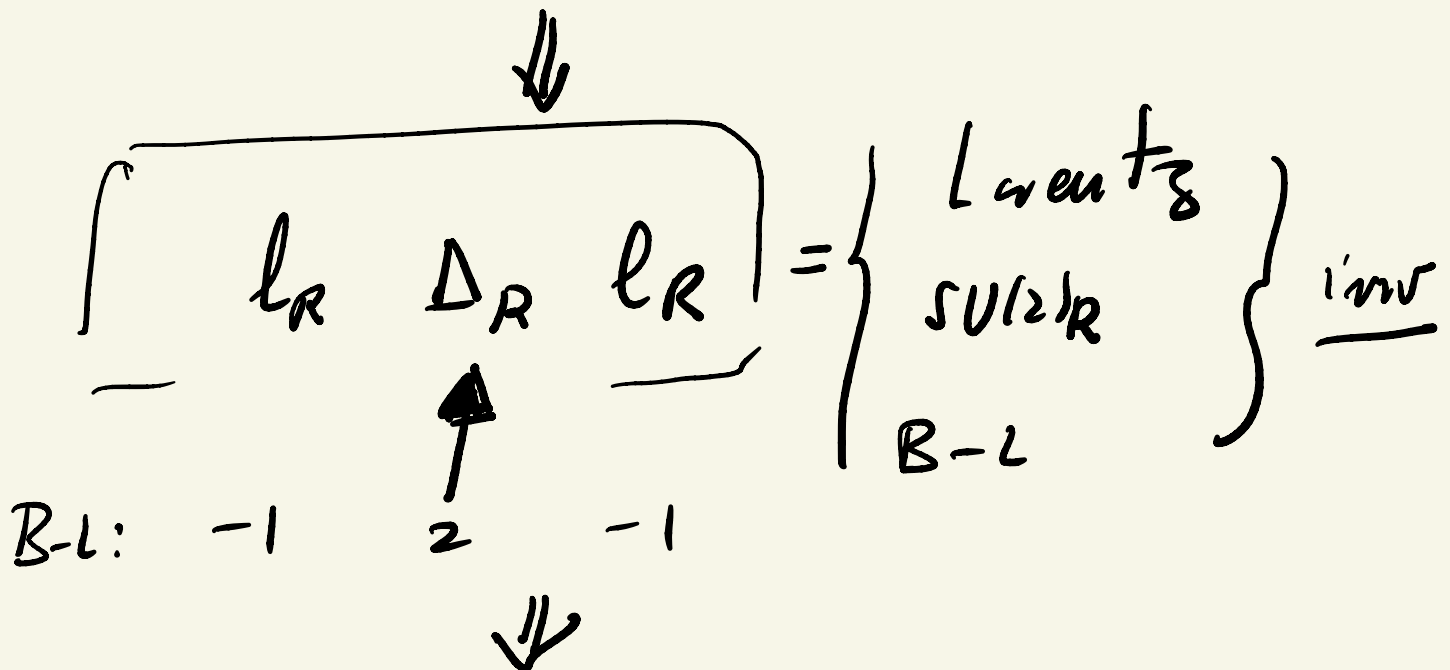
\Downarrow favor l_R

(a) ~~$\bar{l}_R \Delta_R l_R$~~ ; (b) $l_R \Delta_R l_R$

$$\begin{aligned}
 l_R &\equiv R l \Rightarrow \bar{l}_R l_R = (R l)^\dagger \gamma^0 R l \\
 &= l^\dagger R^\dagger \gamma^0 R l \\
 &= l^\dagger \gamma^0 L R l = 0
 \end{aligned}$$

$$\bar{l}_R \gamma^\mu l_R = \text{Lorentz}_3 \text{ or } U_1$$

$$\bar{l}_L l_R = \text{Lorentz}_3 \text{ inv.}$$



- $(B-L) \Delta_R = 2 \Delta_R \Leftrightarrow (B-L) l_R = -l_R$ ✓

- $l_R l_R = 2_R \times 2_R = \cancel{1_R} + 3_R$

We must break $SU(2)_R$

($M_{WR}, M_{ZR} \propto \langle \Delta_R \rangle$)



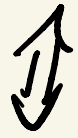
$$\Delta_R = U_R \Delta_R U_R^\dagger \quad (\text{adjoint})$$

$$\text{Tr} \Delta_R = 0, \quad \Delta_R = \Delta_R^\dagger$$

$$(B-L) \Delta_R = 2 \Delta_R \Rightarrow \Delta_R \neq \Delta_R^\dagger$$

$$(B-L) \Delta_R^\dagger = -2 \Delta_R$$

$\Delta_R = \text{"complex"}$




$$\Delta_R = \Delta_R^1 + i \Delta_R^2$$

$$\therefore \Delta_R^1 = (\Delta_R^1)^*$$

$$\Delta_R^2 = (\Delta_R^2)^*$$



$$\mathcal{L}_y(\Delta) = Y_{\Delta_R} l_R^T C i \sigma_2 \Delta_R l_R +$$

$L \leftrightarrow R$  $Y_{\Delta_L} l_L^T C i \sigma_2 \Delta_L l_L + h.c.$

P: $Y_{\Delta_L} = Y_{\Delta_R} \equiv Y_{\Delta}$

$$l_R^T C i \sigma_2 \Delta_R l_A \rightarrow$$

$$\rightarrow l_R^T U_R^T i \sigma_2 U_R \Delta_R U_R^T U_R C l_R$$

$$= l_R^T i \sigma_2 \underbrace{U_R^T U_R}_{1} \Delta_R \underbrace{U_R^T U_R}_{1} C l_R \quad \checkmark$$

⇓

$$\mathcal{L}_4 = \frac{1}{\Lambda} l_R^T i \sigma_2 C \Delta_R l_A + R \rightarrow L$$

th.c.

$$\Delta \rightarrow U \Delta U^\dagger = e^{i \vec{\theta} \cdot \vec{T}} \Delta e^{-i \vec{\theta} \cdot \vec{T}}$$

$$= \Delta + i \vec{\theta} \cdot [\vec{T}, \Delta] + \dots$$

$$\hat{T} \Delta = [\hat{T}, \Delta] \quad \hat{T} \equiv \hat{\sigma}_3 / 2$$

$$\Delta = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\hat{T}_3 \Delta = \frac{1}{2} \left[\begin{pmatrix} a & +b \\ -c & -d \end{pmatrix} - \begin{pmatrix} a & -b \\ +c & -d \end{pmatrix} \right]$$

$$= \begin{pmatrix} 0 \cdot a & +b \\ -c & 0 \cdot d \end{pmatrix}$$

$$Q_{em} = \hat{T}_{3L} + \hat{T}_{3R} + \frac{B-L}{2}$$

⇓

$$Q_{em} \Delta_R = \hat{T}_{3R} \Delta_R + \Delta_R$$

$$\text{Qew } \Delta_R = \begin{pmatrix} 1.a & 2.b \\ 0.c & 4.d \end{pmatrix}$$

$$\Delta_R = \begin{pmatrix} \frac{1}{\sqrt{2}} d_R^+ & d_R^{++} \\ d_R^0 & -d_R^+/\sqrt{2} \end{pmatrix}$$

$$\Delta_L = \begin{pmatrix} \frac{1}{\sqrt{2}} d_L^+ & d_L^{++} \\ d_L^0 & -d_L^+/\sqrt{2} \end{pmatrix}$$

$$\underline{Y_R}: (1) \langle \Delta_L \rangle = 0 \quad (?)$$

$$(2) \langle \Delta_R \rangle = \begin{pmatrix} 0 & 0 \\ v_R & 0 \end{pmatrix} (?)$$

(1) \cancel{P} spontaneous

$$\langle \Delta_L \rangle = 0, \quad \langle \Delta_R \rangle \neq 0$$

(2) $\Delta_R \rightarrow$ how to "know" the
cause Q_{em} ?

(1) $\phi_L \xleftrightarrow{D=P} \phi_R$

$$\therefore \langle \phi_L \rangle = 0, \quad \langle \phi_R \rangle \neq 0$$

D: $V = -\frac{\mu^2}{2} (\phi_L^2 + \phi_R^2) \leftrightarrow P$
(equal)

$$+ \frac{\lambda}{4} (\phi_L^4 + \phi_R^4) \quad \leftarrow P$$

equal

$$+ \frac{\lambda'}{2} \phi_L^2 \phi_R^2$$

$$= -\frac{\mu^2}{2} (\phi_L^2 + \phi_R^2) + \frac{\lambda}{4} (\phi_L^2 + \phi_R^2)^2$$

$$+ \frac{\lambda' - \lambda}{2} \phi_L^2 \phi_R^2$$

(a) $\lambda' = \lambda \Rightarrow$ flat direction

$$\boxed{\langle \phi_L^2 \rangle + \langle \phi_R^2 \rangle = \mu^2 / \lambda} \quad (*)$$

not realistic

(b) $\lambda' - \lambda$ determines the breaking

$$b1. \lambda' - \lambda > 0$$

$$\Rightarrow \left[\begin{array}{l} \langle \phi_L \rangle = 0, \langle \phi_R \rangle \neq 0 \\ \text{(from *)} \end{array} \right]$$

$$\langle \phi_R \rangle = 0, \langle \phi_L \rangle \neq 0 \uparrow$$

$$b2. \lambda' - \lambda < 0 \text{ \& maximizes}$$

$$\Rightarrow \langle \phi_L \rangle \neq 0 \neq \langle \phi_R \rangle$$

\Downarrow

$$\langle \phi_L \rangle = \langle \phi_R \rangle$$

$$\begin{aligned} \frac{\partial V}{\partial \phi_L} &= -\mu^2 \phi_L + \lambda \phi_L^3 + \lambda' \phi_L \phi_R^2 \\ &= (-\mu^2 + \lambda \phi_L^2 + \lambda' \phi_R^2) \phi_L = 0 \end{aligned}$$

$$\frac{\partial V}{\partial \phi_R} = -\mu^2 \phi_R + \lambda \phi_R^3 + \lambda' \phi_R \phi_L^2$$

$$= (-\mu^2 + \lambda \phi_R^2 + \lambda' \phi_L^2) \phi_R = 0$$

$$\Rightarrow \bullet \langle \phi_L \rangle = \langle \phi_R \rangle = 0 \Leftrightarrow$$

local maximum

$$\bullet \langle \phi_L \rangle \neq 0 \neq \langle \phi_R \rangle$$

$$\Rightarrow \langle \phi_L \rangle = \langle \phi_R \rangle$$

$$\bullet \langle \phi_L \rangle = 0, \langle \phi_R \rangle \neq 0$$

or vice-versa



$$\lambda' - \lambda > 0$$



$$\langle \phi_L \rangle = 0, \quad \langle \phi_R \rangle \neq 0$$

↓ gauge case

• $\phi_{L,R} = \text{doublet}$

$$\Rightarrow \phi_L^\dagger \phi_L, \quad \phi_R^\dagger \phi_R$$

$$\lambda \left[(\phi_L^\dagger \phi_L)^2 + L \leftrightarrow R \right]$$

$$\lambda' \phi_L^\dagger \phi_L \phi_R^\dagger \phi_R$$

• $\phi_{L,R} = \text{doublet}$

$$\text{Tr} \Delta_{L,R}^\dagger \Delta_{L,R}$$

$$\phi_L^2 \rightarrow (\text{Tr} \Delta_L^\dagger \Delta_L)^2$$

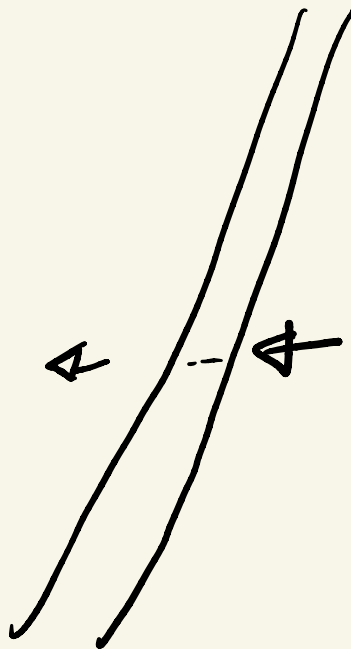
etc.

To be studied :

$$\langle \Delta_R \rangle \neq 0$$

$$\langle \Delta_L \rangle = 0$$

domain 1



$$\langle \Delta_L \rangle \neq 0$$

$$\langle \Delta_R \rangle = 0$$

domain 2

size of domain =

size of causal contact

$$(2) \langle \Delta_R \rangle \stackrel{?}{=} \begin{pmatrix} 0 & 0 \\ \nu_R & 0 \end{pmatrix}$$

↑
neutral component

$$V = -\frac{\mu^2}{2} T_1 \Delta^\dagger \Delta + \frac{\lambda}{4} (T_1 \Delta^\dagger \Delta)^2$$

$$+ \frac{\lambda'}{4} T_2 \Delta^\dagger \Delta \Delta^\dagger \Delta$$

$$+ \frac{\lambda''}{4} \text{Tr} \Delta^2 \cdot \text{Tr} (\Delta^+)^2$$

*** Prove that there are only two invariants

$$\Leftrightarrow \text{Tr} \Delta^+ \Delta \Delta^+ \Delta = a (\text{Tr} \Delta^+ \Delta)^2 + b \text{Tr} \Delta^2 \text{Tr} (\Delta^+)^2$$



$$V = -\frac{\mu^2}{2} \text{Tr} \Delta^+ \Delta + \frac{\lambda_1}{4} (\text{Tr} \Delta^+ \Delta)^2$$

$$+ \frac{\lambda_2}{4} \text{Tr} \Delta^2 \text{Tr} (\Delta^+)^2$$

$$\langle \Delta \rangle \neq 0$$

$$\Delta = \Delta_1 + i \Delta_2 \quad \Delta_i^+ = \Delta_i$$

\Downarrow

$$\Delta_1 = \Delta_1^+ + \Delta_1 \rightarrow U \Delta U^+$$

\Downarrow

$$\langle \Delta_1 \rangle = \begin{pmatrix} a & 0 \\ 0 & -a \end{pmatrix}, \quad a \in \mathbb{R}$$

$$\langle \Delta_2 \rangle = \begin{pmatrix} b & c \\ c^* & -b \end{pmatrix}, \quad \begin{array}{l} b \in \mathbb{R} \\ c \in \mathbb{C} \end{array}$$

$$\langle \Delta \rangle = \begin{pmatrix} a & 0 \\ a & -a \end{pmatrix}$$

$$SU(2) \xrightarrow{\langle \Delta_1 \rangle} U(1) (T_3)$$

$$\frac{1}{T_3} \langle \Delta_1 \rangle = [T_3, \langle \Delta_1 \rangle] = 0$$

$$\Rightarrow U_3 = e^{i\theta 2T_3} = e^{i\theta} \sigma_3 = \text{unitary}$$

$$U_3 = \cos \theta + i \sin \theta T_3 = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

⇓

$$\langle \Delta_2 \rangle \rightarrow \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \begin{pmatrix} b & c \\ c^* & -b \end{pmatrix} \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix}$$

$$= \begin{pmatrix} b & c e^{2i\theta} \\ c^* e^{-2i\theta} & -b \end{pmatrix} \Rightarrow \begin{cases} c e^{2i\theta} = \nu \\ c^* e^{-2i\theta} = \nu \end{cases}$$

$(r \in \mathbb{R})$

$$\Downarrow$$
$$\langle \Delta_2 \rangle = \begin{pmatrix} b & r \\ r & -b \end{pmatrix}$$

\Downarrow

$$\langle \Delta \rangle = \langle \Delta_1 \rangle + i \langle \Delta_2 \rangle$$

$$= \begin{pmatrix} z & ir \\ ir & -z \end{pmatrix} \quad \begin{array}{l} z = a + ib \\ r \in \mathbb{R} \end{array}$$

$$\langle \Delta \rangle \equiv \langle \Delta_R \rangle = \begin{pmatrix} 0 & 0 \\ 0_R & 0 \end{pmatrix}$$

PUZZLE!

$$\langle \Delta^\dagger \rangle = \begin{pmatrix} z^* & -iv \\ -iv & -z^* \end{pmatrix}$$

\Downarrow

$$T_1 \Delta^\dagger \Delta = (|z|^2 + v^2) \mathcal{L}$$

$$T_1 \Delta^2 = (z^2 - v^2) \mathcal{L}$$

\Downarrow

$$\bar{V} = \mu^2 (|z|^2 + v^2) + \lambda_1 (|z|^2 + v^2)^2$$

$$+ \lambda_2 (z^2 - v^2) (z^{*2} - v^2)$$

$$\lambda_2 = 0 \Rightarrow \left[\text{flat } |z|^2 + v^2 = \mu^2 / \lambda_1 \right]$$

$$\Downarrow \left[(z^2 - v^2) (z^{*2} - v^2) \geq 0 \right]$$

$$(i) \quad \lambda_2 > 0 \Rightarrow \boxed{z^2 = v^2}$$

$$\Rightarrow \langle \Delta \rangle = \begin{pmatrix} \pm 1 & i \\ i & \mp 1 \end{pmatrix} v$$

must be!!!

choose: $\langle \Delta \rangle = \begin{pmatrix} 1 & i \\ i & -1 \end{pmatrix} v$

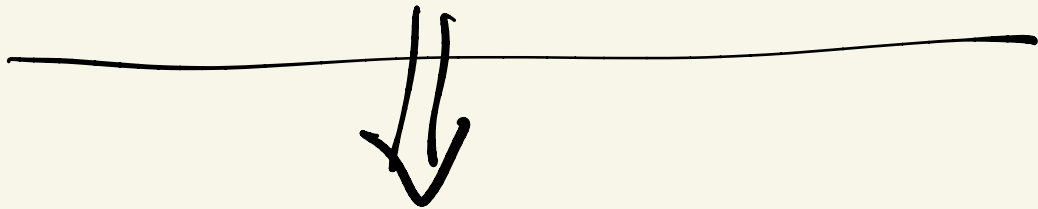
$$(ii) \quad \lambda_2 < 0 \Rightarrow \gamma = 0 \quad \omega = z = 0$$

$$\Rightarrow \langle \Delta \rangle = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \equiv \omega$$

$$\} \langle \Delta \rangle = \begin{pmatrix} v & 0 \\ 0 & -v \end{pmatrix}$$

Equivalent

$$\neq \begin{pmatrix} 0 & 0 \\ v & 0 \end{pmatrix}$$



(i) must be true!

$$\langle \Delta \rangle = \begin{pmatrix} 1 & i \\ i & -1 \end{pmatrix} v$$

$$\neq \begin{pmatrix} 0 & 0 \\ v & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & i \\ i & -1 \end{pmatrix} = U \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} U^{\dagger}$$

find $U = ?$